

A SOFTWARE PACKAGE
FOR ANALYSIS
OF GEOPHYSICAL MEASUREMENTS

John Frederick Arfman, Jr.

United States Naval Postgraduate School



THESIS

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OF GEOPHYSICAL MEASUREMENTS

by

John Frederick Arfman, Jr.

Thesis Advisor:

H. A. Titus

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A Software Package for Analysis
of Geophysical Measurements

by

John Frederick Arfman, Jr.
Ensign, United States Navy
B.S., University of New Mexico, 1970

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ABSTRACT

A software package for general analysis of real time series for geophysical data was developed. The package consists of FORTRAN IV callable subprograms that are assigned different tasks such as input, output (either printed or graphical), initial data analysis and filtering, spurious data rejection, FFT, and spectral analysis. A geophysical problem involving detection of unusual deep ocean pressures was analyzed.

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I. INTRODUCTION

The types of real time series considered here are geophysical processes. Usually, time is the independent variable and such quantities as velocity and direction of flow, temperature, and pressure are the dependent variables. In the analysis and design of geophysical experiments, it is useful to have at one's disposal a set of software subroutines to aid in this analysis. Thus, a software package for general analysis of real time series geophysical data was developed. The package consists of FORTRAN IV callable subprograms that are assigned different tasks such as input, output (either printed or graphical), initial data analysis and filtering, spurious data rejection, FFT, spectral analysis, and so forth. A geophysical problem involving detection of unusual deep ocean pressures was analyzed.

II. A GEOPHYSICAL PROBLEM

A. STATEMENT OF THE PROBLEM

Throughout nature there exist many phenomenon that occur only as "unusual events." In the realm of oceanography one such unusual event is called a tsunami. The word tsunami comes from the Japanese and means storm wave. It is known that the presence of a tsunami is indicated by a definite change in water pressure. Other information concerning the velocity and direction of the current, water temperature, salinity, and so forth, would also be useful in the analysis and understanding of these events. However, the infrequent rate at which tsunamis occur makes their observation difficult. In order to analyze and predict these events, methods were devised to detect and record them. The problem then is to logically design a detector that will automatically sense the presence of a tsunami and cause all the pertinent data to be recorded.

B. A MODEL

In order to determine the presence of an unusual event, a detector which receives digitized pressure data was designed [1]. Throughout the following discussion refer to Figure 1 for the logical design of the detector. The detector can be divided into six logically separate sections.

Data Input. Digital pressure sensors of varying degrees of sophistication and reliability are presently

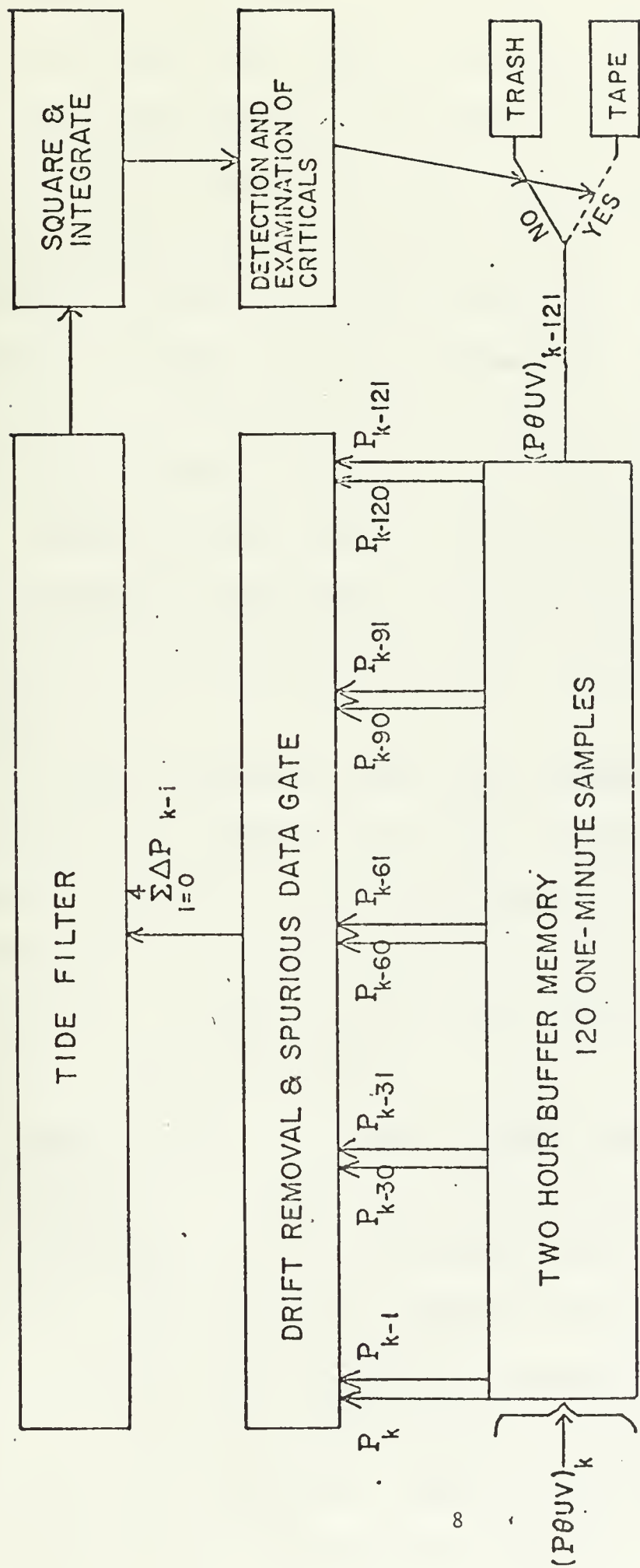


FIG. 1 BLOCK DIAGRAM OF UNUSUAL EVENT DETECTOR, IN THE EVENT OF A "CRITICAL" THE ENTIRE BUFFER, CONTAINING PRESSURE, TEMPERATURE AND VELOCITY COMPONENTS FOR THE LAST 120 ONE-MINUTE SAMPLES, IS WRITTEN ON TAPE (AND RETAINED IN BUFFER).

THE ABOVE SCHEMATIC REFERS TO DETECTION OF AN EVENT BAND OF PRESSURE; SIMILAR "CRITICALS" CAN BE TRIGGERED BY THE TEMPERATURE AND VELOCITY READINGS (Not shown).

available on the commercial market. Digital sensors generally count the number of cycles of a pressure sensitive oscillator over a given time interval. This summation in effect integrates the pressure signal. The integration process serves as a low pass filter. That is, high frequency pressure variations relative to the sampling interval tend to average out, thus contributing equally to each sample. This filtering of high frequency variations might prove undesirable in some applications. For this particular problem, however, almost all of the high frequency variations are naturally filtered out because of attenuation of pressure variations due to ocean depth.

It was determined that the frequency band in which tsunamis occur extends from $\frac{1}{4}$ to 30 cycles per hour. Nyquist frequency theory indicates that in order to detect a frequency of N cph, a sampling rate of at least 2N cph is required. Hence the sampling interval was determined to be one sample per minute.

Input Buffer. An input buffer receives the most recent pressure reading in digitized form. The actual hardware implementation of the input buffer is not part of the problem. Conceivably the input buffer could be anything from an acoustic delay line to a magnetic core.

The buffer is large enough to retain the most recent 121 consecutive samples. Hence, a two hour history of pressure data is available for analysis at any one time.

Figure 2(a) is a plot of typical pressure data over an 80 hour period.

First Differencing. The presence of a tsunami could be indicated by an abnormal change in pressure from one point in time to another. The phrase "change in pressure" indicates that the derivative should be computed. As a close approximation to the derivative, the positive first difference was determined.

Incorporated within the first differencer was a spurious data gate. Here each first difference was compared against a preset threshold value. If the threshold value was exceeded, then a sensor error (spurious error) was the probable cause since deep-ocean pressure changes are relatively small in amplitude. Since such an erroneous first difference might falsely indicate the presence of a tsunami, an excessive first difference was set equal to the previous first difference. The threshold value was determined after analysis of test data. First differencing, as computing the first derivative, removes the mean pressure value and suppresses drift. Figure 2(b) illustrates the effect of first differencing on the data of Figure 2(a).

Tide Filter. The purpose of the tide filter is to remove the effects of the diurnal and semi-diurnal tides. This was accomplished by forming a weighted sum from the sample data at $\frac{1}{2}$ hour intervals. The coefficients were determined from analysis of the tidal spectrum. The tide filter output then is:

$$D_t = dP_t - 3.920392 \cdot dP_{t-30} + 5.841800 \cdot dP_{t-60} \\ - 3.920392 \cdot dP_{t-90} + dP_{t-120}$$

where dP_t is the first difference at time t [2].

Figure 2(c) shows the effect of the tide filter on the first differenced data of Figure 2(b). Note how the tide filter extended the effects of a spurious data value when there was no spurious data gating.

Rectification. As Figure 2(c) shows, the output of the tide filter presents an erratic picture of the changes in pressure. In order to observe any trends in this data, an integral over some fixed period of time needed to be computed. Any integration of the tide filtered data would only produce a result close to zero. This problem was overcome by taking the absolute value of the data in two ways; that is, the negative data values were made positive so that the data was no longer distributed about zero. The most straightforward method was to simply ignore the sign (i.e., rectification) of each number outputted from the tide filter. The second method was to square each value. Figure 2(d) shows the result of squaring the tide filter output.

Integration and Detection. The rectified or squared tide filtered data was then integrated. The method of integration was based on the solution of a differential equation. The general form of the integrating function is:

$$y_{t+1} = e^{-\alpha} (y_t + x_t) , \quad t = 1, 2, 3, \dots \text{ minutes}$$

and where $y_1 = 0$,

α = a time constant associated with the interval of integration,

x_t = the data to be integrated (rectified or squared output of tide filter).

The value of α was determined experimentally via the simulation ($\alpha = 1/60$). Figure 2(e) is a plot of the integrated tide filtered pressure data after the squaring process.

Dependent on the value of α , a critical threshold value had to be chosen such that whenever the integrated signal exceeded this value, a switch was closed causing the contents of the buffer to be recorded on a tape or otherwise be permanently recorded. At the end of a two hour period of normal input the buffer would once again be recorded. At this point the value of the integrated signal would be tested again. If the integrated signal was still greater than the threshold value, then the buffer would again be recorded after two hours; otherwise after two hours the testing is resumed as before. This technique guarantees that a minimum four hour record will be available for each event detected.

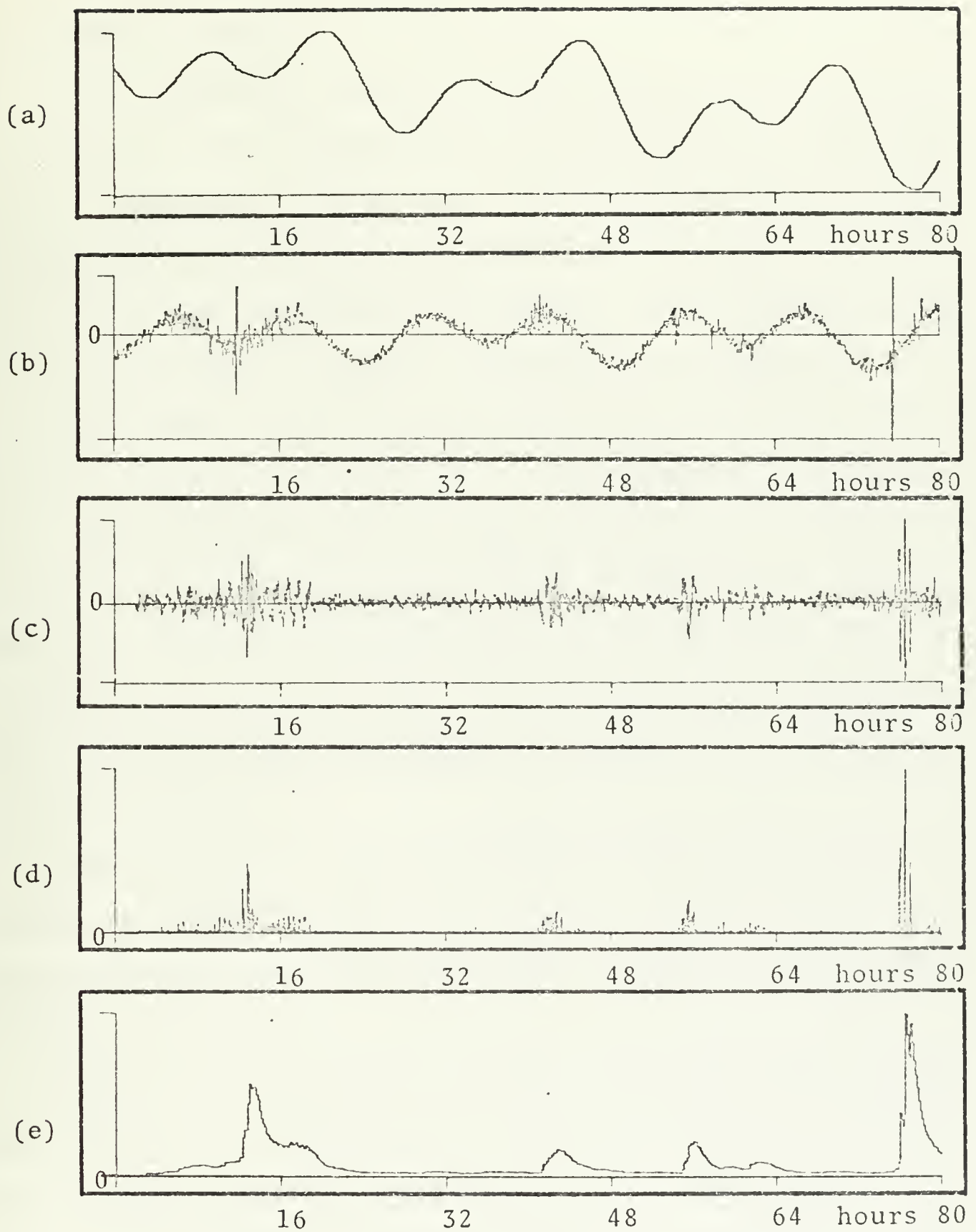


FIGURE 2. (a) Pressure, (b) First Differenced Pressure (spurious Data Gate Off), (c) Tide Filtered Pressure, (d) Squared Tide Filtered Data, (e) Integrated Signal Versus Time in Hours.

III. A SOFTWARE SIMULATION

A. GENERAL APPROACH

To be generally useful a software package must be able to simulate a real system on the level of logical components. That is, the basic information extracting procedures of the system must be available for graphical or statistical analysis during the simulation. Accordingly, the following set of eighteen FORTRAN callable subprograms was developed. The subprograms and their associated formal parameter are listed alphabetically in Table I. The subprogram UNIFORM is a function subprogram and XYAXIS is an entry in DRAW1. Otherwise all the subprograms listed in Table I are subroutines. The various subprograms are explained in the following sections according to their use in the unusual event problem. Each subprogram is listed in its entirety in the Appendix.

Each subroutine uses the variable FILE as its first formal parameter. The meaning and use of FILE will be given once here to avoid duplication in the sections which follow.

FILE is a real-valued variable identifying the current data file. This number is for user identification purposes only. FILE is usually set equal to 1.0 or the DO-loop index if the simulation is being performed iteratively. When a subroutine is called, a message is printed indicating that the subroutine has completed its task. The message is of the form:

SUBROUTINE	FORMAL PARAMETERS	PAGE
ANTIDE	(FILE, Y, TIDE, L)	<u>26</u>
CARDS	(FILE, Y, L)	<u>16</u>
DRAW1	(FILE, Y, L, YMAX, YMIN, LOG, XL, XI)	<u>29</u>
FFREAL	(FILE, A, B, N, ISN)	<u>23</u>
FFT	(FILE, A, B, N, ISN)	<u>23</u>
FIRSTD	(FILE, Y, DIFF, L, THRESH)	<u>25</u>
HARMON	(FILE, Y, YH, L, H1, H2)	<u>24</u>
INTGRL	(FILE X, Y, L, FTC)	<u>27</u>
OUTPUT	(FILE, Y, L)	<u>28</u>
PACK	(FILE, Y, L, Y2, L2, IDEN, RAMP, ISEED)	<u>19</u>
POWER	(FILE, Y, L, XL, XI)	<u>25</u>
RECSQR	(FILE, Y, Y2, L, IRS)	<u>26</u>
RESET	(FILE, Y, L, Y2, L2)	<u>18</u>
SCAN	(FILE, Y, L, YMEAN, YSTDEV, L2)	<u>17</u>
STATS	(FILE, Y, L, YMAX, YMIN, YMEAN, YSTDEV)	<u>17</u>
TAPE	(FILE, Y, L)	<u>16</u>
UNIFRM	(ISEED)	<u>22</u>
XYAXIS	(XAL, YAL)	<u>29</u>

TABLE I.

Subroutine Names, Formal Parameters, and Page References.

FILE NO. XX.X "message".

The digits XX.X indicate the current value of FILE. Execution of subroutine DRAW1 causes FILE to be incremented by 0.1.

B. DATA INPUT

CALL CARDS (FILE, Y, L)

CALL TAPE (FILE, Y, L)

Data input is accomplished by calling one of the above subroutines. The meaning of each of the formal parameters is:

FILE - see Section III.A.

Y - A real, singly dimensioned array into which the data is to be read.

L - An integer-valued variable equal to the size of array Y. In subroutine CARDS, L must equal the number of data elements to be read-in. In subroutine TAPE, L may equal the number of data elements to be read-in, or it may equal the maximum size of Y as defined in the DIMENSION statement of the main program. If an end-of-file mark is encountered on the tape before the L data elements have been read, the subroutine halts and returns the number of elements actually processed as the value of L.

These subroutines should be reloaded with the proper FORMAT statements inserted before the simulation is run. Currently the FORMAT is (10F7.0,F10.0).

C. INITIAL SCAN OF DATA

```
CALL STATS (FILE, Y, L, YMAX, YMIN, YMEAN, YSTDEV)
CALL SCAN (FILE, Y, L, YMEAN, YSTDEV, L2)
```

It is sometimes the case when geophysical data is being recorded that the initial start up of the sensing device introduces spurious data which is recorded as valid data. Used in series, subroutines STATS and SCAN can determine the extent of any start up noise present in the data.

The meaning of each of the formal parameters is:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be analyzed. Neither subroutine alters the contents of array Y in any way.

L - An integer-valued variable equal to the size of array Y.

YMAX - A real-valued number returned by subroutine STATS equal to the maximum value encountered in array Y.

YMIN - A real-valued number returned by subroutine STATS equal to the minimum value encountered in array Y.

YMEAN - A real-valued number returned by subroutine STATS equal to the statistical mean of the data in array Y.

YSTDEV - A real-valued number returned by subroutine STATS equal to the standard deviation of the data in array Y.

L2 - An integer-valued number returned from sub-routine SCAN equal to the number of noise dependent elements in array Y as determined from the following procedure.

- 1) set I=1, set ITEST=0.
- 2) If $\text{ABS}(Y(I) - Y\text{MEAN}) > 2 * \text{STDEV}$ then set
 ITEST=0, set L2=I;
 otherwise, set ITEST=ITEST+1.
- 3) If ITEST > 100 then return; otherwise
 set I=I+1, go to step 2.

D. ADJUSTING THE SAMPLING INTERVAL

```
CALL RESET     (FILE, Y, L, Y2, L2)
CALL PACK      (FILE, Y, L, Y2, L2, IDEN, RAMP, ISEED)
UNIFRM         (ISEED)
```

The sample size of data to be analyzed can be adjusted in two basic ways. First, the sampling interval may be shifted forward by any specified amount. For example, if preliminary analysis of the data indicates that the initial data elements are in error, then the data file can be re-set so that the record begins later in the sequence, thereby skipping the bad data. This is accomplished by a call on subroutine RESET. The formal parameters of RESET are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be reset.

L - An integer-valued variable equal to the size of array Y.

- Y2 - A real-valued, singly dimensioned array into which the reset elements of array Y are to be loaded. Arrays Y and Y2 may be the same physical array in which case the skipped data is overlayed and lost to further processing.
- L2 - An integer-valued variable. On the initial call to RESET, L2 equals the number of data elements in array Y which are to be skipped. On return, L2 equals the size of array Y2.

The second method of adjusting the sampling interval involves increasing the density of the data points. This is accomplished by a call on subroutine PACK. The formal parameters of PACK are:

- FILE - see Section III.A.
- Y - A real-valued, singly dimensioned array containing the data to be packed.
- L - An integer-valued variable equal to the size of array Y.
- Y2 - A real-valued, singly dimensioned array into which the expanded (packed) data of array Y is to be placed. Arrays Y and Y2 may be the same physical array.
- L2 - An integer-valued variable. On the initial call to the subroutine, L2 must equal the maximum size of array Y2 as declared in the dimension statement of the main program. On return, L2 will equal the size of array Y2

as declared in the dimension statement of the main program. On return, L2 will equal the size of array Y2 if the subroutine completed successfully. The size of array Y2 can be determined from the formula $(L-1) \times IDEN + 1$.

- IDEN - An integer-valued variable specifying the multiple of the current density that is desired. The value of IDEN in part determines the value of L2 that is returned to the main program. IDEN can also be interpreted to mean that IDEN-1 points are embedded between each of the original points in array Y.
- RAMP - A real-valued variable equal to the maximum variability allowed when the embedded points are being computed. If RAMP = 0.0 then the embedded points are determined by linear interpolation between successive Y values; otherwise, the value of RAMP is multiplied by a uniformly random number between $-\frac{1}{2}$ and $\frac{1}{2}$, and this value is added to the interpolated value.
- ISEED - An integer-valued variable that serves as the random number seed for a random number generator. ISEED should be a six digit integer equal to $\pm 3 \pmod{8}$.

Conceptually subroutine PACK embeds the data as shown in Figure 3.

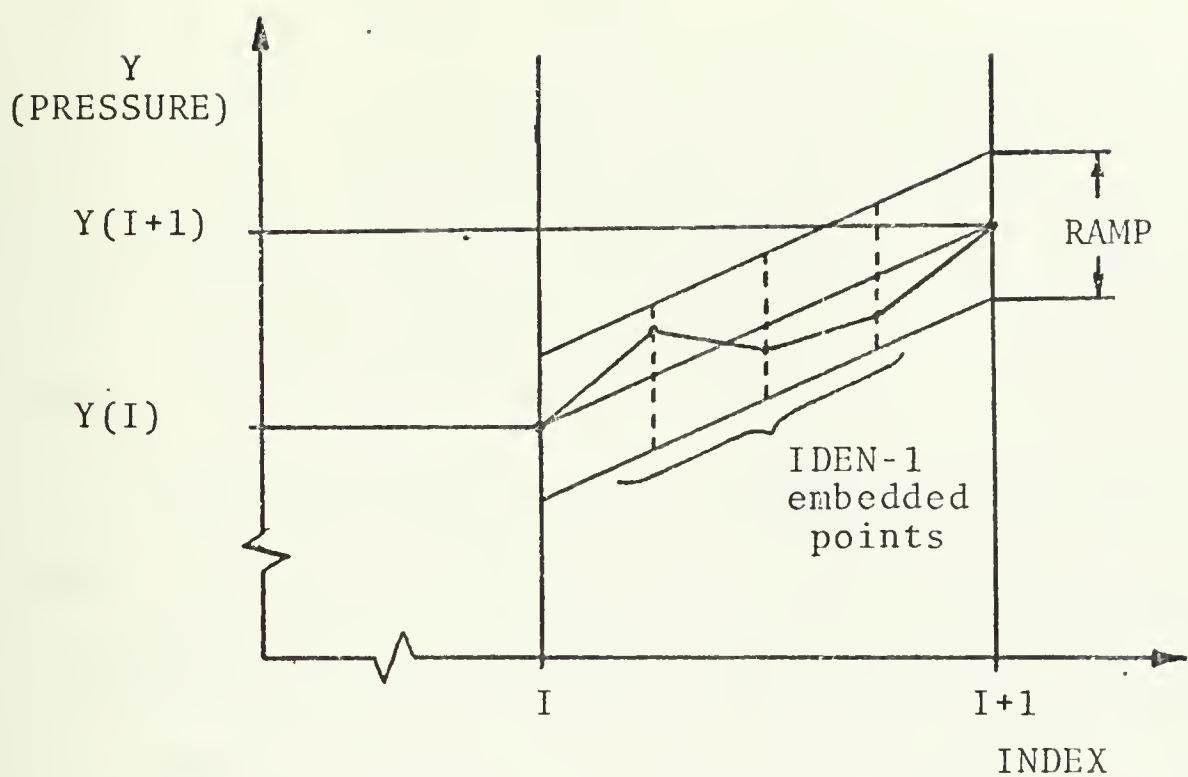


FIGURE 3.

Conceptual Operation of Subroutine PACK where $RAMP > 0$ and $IDEN = 4$.

Function subprogram UNIFORM returns a uniformly random number between $-\frac{1}{2}$ and $\frac{1}{2}$. The use of UNIFORM is not restricted to subroutine PACK.

The original data used in the simulation was based on a four minute sampling interval. The detector, however, was designed to operate on one minute data. Hence, to obtain the proper sampling interval the following call was made on subroutine PACK.

```
CALL PACK (FILE, Y, L, Y, LMAX, 4, 0.0, 103941)
```

LMAX equals the maximum size of array Y as dimensioned in the main program. Note RAMP equals zero.

E. FOURIER ANALYSIS

```
CALL FFREAL (FILE, A, B, N, ISN)
```

```
CALL FFT (FILE, A, B, N, ISN)
```

```
CALL HARMON (FILE, Y, YH, L, H1, H2)
```

```
CALL POWER (FILE, Y, L)
```

Three areas of Fourier analysis are provided for in the software package. Subroutine FFREAL returns the Fourier cosine and sine coefficients of the data passed to it. Subroutine HARMON returns the approximation to the data passed to it on the basis of the H1 through H2 harmonics. Subroutine POWER returns the power spectrum of the data. Subroutine HARMON and POWER both call on FFREAL, and FFREAL in turn calls on subroutine FFT. Subroutines FFREAL and FFT are variations of Singleton's [3] algorithms for mixed radix fast Fourier transform.

The formal parameters of subroutine FFT are:

- FILE - see Section III.A.
- A, B - Real-valued, singly dimensioned arrays. Arrays A and B originally hold the real and imaginary parts of the data and return the real and imaginary Fourier coefficients.
- N - An integer-valued variable equal to the number of real (or imaginary) data elements. In the context of this paper, $N=L/2$.
- ISN - An integer-valued variable. The magnitude of ISN determined the step size of data in arrays A and B. The sign of ISN determines whether the complex or inverse transform will be performed.

The formal parameters for subroutine FFREAL are:

- FILE - see Section III.A.
- A, B, - Real-valued, singly dimensioned arrays. The original data values are alternately stored in arrays A and B. On return, arrays A and B hold the cosine and sine coefficients respectively, of the transform.
- N - An integer-valued variable equal to the number of elements in array A. In the context of this paper, $N=L/2$.
- ISN - An integer-valued variable. The magnitude of ISN determines the step size within arrays A and B. If the magnitude of ISN is 1, then

each consecutive element of the array is used in the computations. If the magnitude is 2, every other element is used. Hence, if the data is contained within a single array, say X, rather than two separate ones, the call to FFREAL would be

```
CALL FFREAL (X, X(2), N, 2).
```

If the sign of ISN is negative, then the inverse transform is computed.

The formal parameters of subroutine HARMON are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array originally containing the data to be analyzed. On return array Y contains the Fourier cosine and sine coefficients as returned from FFREAL.

YH - A real-valued, singly dimensioned array which on return holds the approximation based on the H1 and H2 harmonic of the data originally contained in array Y. This process involves a double summation and could be time consuming depending on the values of H1 and H2.

L - An integer-valued variable equal to the size of array Y (or array YH).

H1, H2 - Positive integer-valued variables indicating which harmonics, H1 through H2, inclusive, of array Y are to be isolated.

The formal parameters of subroutine POWER are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data which is to have its power spectrum computed. On return, the power spectrum coefficients are in the first $N=L/2$ elements of array Y.

L - An integer-valued variable equal to the size of array Y.

F. FIRST DIFFERENCING

CALL FIRSTD (FILE, Y, DIFF, L, THRESH)

Subroutine FIRSTD computes the positive first difference of the data in array Y, and returns the array of first differences in array DIFF. The first and last elements of DIFF are zero. Subroutine FIRSTD is so coded that arrays Y and DIFF may be the same physical array. By setting THRESH to any computed value, any first difference greater than THRESH will cause that first difference to be set equal to the previous first difference.

The formal parameters of subroutine FIRSTD are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be first differenced.

DIFF - A real-valued, singly dimensioned array which returns the positive first differences of the data in array Y.

L - An integer-valued variable equal to the size of array Y (or array DIFF).

THRESH - A real-valued variable against which each first difference is compared. If the current first difference is greater than THRESH (threshold value), then the first difference is set equal to the previous first difference.

G. TIDE FILTER

CALL ANTIDE (FILE, Y, TIDE, L)

Geophysical events usually occur in the domain of other less interesting phenomenon. In the case of the unusual event detector, one such phenomenon is the effect of the tides, both diurnal and semi-diurnal. Subroutine ANTIDE (anti-tide) filters out the combined effect of these tides.

The formal parameters of subroutine ANTIDE are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be tide filtered.

TIDE - A real-valued, singly dimensioned array into which the tide filtered data is placed. Arrays Y and TIDE may be the same physical array.

L - An integer-valued variable equal to the size of array Y (or array TIDE).

H. RECTIFYING THE SIGNAL

CALL RECSQR (FILE, Y, Y2, L, IRS)

Two methods of rectifying the data are provided. The

first involves taking the absolute value of each data value; while the second squares each data value.

The formal parameters of subroutine RECSQR (rectify-square) are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be rectified or squared.

Y2 - A real-valued, singly dimensioned array into which the rectified or squared data is to be placed. Arrays Y and Y2 may be the same physical array.

L - An integer-valued variable equal to the size of array Y (or array Y2).

IRS - An integer-valued variable equal to 1 or 2. If IRS = 1, then the data will be rectified by computing the absolute value of each element. If IRS = 2, then the data will be rectified by computing the square of each element.

I. INTEGRATION

CALL INTGRL (FILE, X, Y, L, FTC)

Integration is performed by multiplying the sum of previous data elements by a fading time constant (FTC); that is some positive number less than unity. The form of the integrating equation is:

$$Y(I) = \text{EXP}(-\text{FTC}) * (Y(I-1) + X(I))$$

where FTC is the fading time constant, and I is the index of the current variable.

The formal parameters of subroutine INTGRL are:

FILE - see Section III.A.

X - A real-valued, singly dimensioned array containing the data to be integrated.

Y - A real-valued, singly dimensioned array into which the integrated data is placed.

L - An integer-valued variable equal to the size of array X (or array Y).

FTC - A real-valued variable. A sample value of FTC could be 1/60.

J. OUTPUT

CALL OUTPUT (FILE, Y, L)

CALL DRAW1 (FILE, Y, L, YMAX, YMIN, LOG, XL, XI)

CALL XYAXIS (XAL, YAL)

Two means of output are provided. Subroutine OUTPUT prints out the first L elements of array Y. The page format of OUTPUT is 200 numbers with index numbers per page.

The formal parameters of subroutine OUTPUT are:

FILE - see Section III.A.

Y - A real-valued, singly dimensioned array containing the data to be printed.

L - An integer-valued variable equal to the number of elements of array Y that are to be printed. L may equal the full size of array Y in which case a large quantity of paper is usually generated.



Subroutine DRAW1 plots the first L elements of array

Y. The formal parameters of subroutine DRAW1 are:

- FILE - see Section III.A.
- Y - A real-valued, singly dimensioned array containing the data to be plotted. Subroutine DRAW1 does not alter the contents of array Y.
- L - An integer-valued variable equal to the number of data points to be plotted.
- YMAX, YMIN - Real-valued variables equal to the maximum and minimum values to be plotted. If $YMAX \leq YMIN$, then the plot is autoscaled.
- LOG - An integer-valued variable equal to 0 or 1. If $LOG = 1$, then the data in array Y is plotted on \log_{10} scale. Otherwise, if $LOG = 0$ the data is plotted in the normal fashion.
- XL, XI - Real-valued, singly dimensioned arrays containing literal constants. The maximum length string allowable is 40 characters. XL is the plot label which may be blank, and XI is the user's identification label.

The lengths of the plot axes are initialized to 20 inches for the x-axis and 8 inches for the y-axis. However, these dimensions may be changed by calling XYAXIS. The formal parameters of XYAXIS are:

- XAL - A real-valued variable equal to the new length of the x-axis in inches.

YAL - A real-valued variable equal to the new length
 of the y-axis in inches. The value of YAL
 should be less than 9 inches.

Subroutine DRAW1 (and XYAXIS) make use of the standard
plot package for the CALCOMP 765 plotter available on the
IBM 360 at the Naval Postgraduate School.

IV. CONCLUSIONS

In the detector, the question arose as to what was the best value of the fading time constant used in the integration scheme. That is, given the form of the integrating equation and that integration is naturally a low pass filter, what value of the fading time constant would produce the most favorable signal-to-noise ratio? Three values of the time constant were chosen, and the integration was performed three times on the squared output of the tide filter with a different time constant in effect each time. The value of the constant used to produce Figure 2 was $1/60$. The significance of this value is that because of the structure of the integrating equation, the contribution of a single data value after one hour's integration would have been reduced to one third of its original effect. This value of the time constant was used. The other two values of the time constant considered were $1/30$ and $1/120$. Table II shows the results of two signal-to-noise ratio computations using the three constants. The two hour "threshold" level to noise ratio was computed by finding a level such that the signal exceeded that level for exactly two hours.

The integrations were performed a second time but the rectified rather than the squared output of the tide filter was used. The ratios computed from these integrations are also given in Table II.

Signal-to-Noise Ratios for Unusual Event Detector	Tide Filter Output	Fading Time Constant= $e^{-\alpha}$	
		$\alpha=1/30.$	$\alpha=1/60.$
Peak Signal to Noise Ratio	Rectified	8.33	5.86
	Squared	45.0	30.0
Two Hour "Threshold" to Noise Ratio	Rectified	4.00	4.44
	Squared	12.0	14.5
			13.5

TABLE II.
SIGNAL-TO-NOISE RATIOS

From examination of Table II, it was determined that a value of $1/60$ for the fading time constant gave the most desirable results when the integration was performed on the squared output of the tide filter. From inspection of the output statistics of the first differences, the standard deviation of the first differenced pressure data was approximately eight. Hence, a three sigma value of 25 was chosen as the threshold value of the spurious data gate in the first differencing subroutine. Figure 4 shows the effect of the spurious data gate on the detector output when this threshold limit was set at 25. Figure 4 also represents a fading time constant value of $1/60$ applied to the integration of the squared output of the tide filter. (Compare Figures 2 and 4.)

The critical threshold value of the unusual event detector was determined to be three times that of the background signal of Figure 4(e). Hence, the three events detected in Figure 4(e) will cause the recorder to be activated.

The power spectra [4] of the tide filter and detector outputs are shown on Figures 5 and 6, respectively. In Figure 5 the null power readings coincide with even cph, and the peaks coincide with odd cph. This result agrees with the characteristics of the tide filter. The nodes of the power spectral plot of the detector output do not exactly agree with those of the tide filter because of the effect of the integration process.

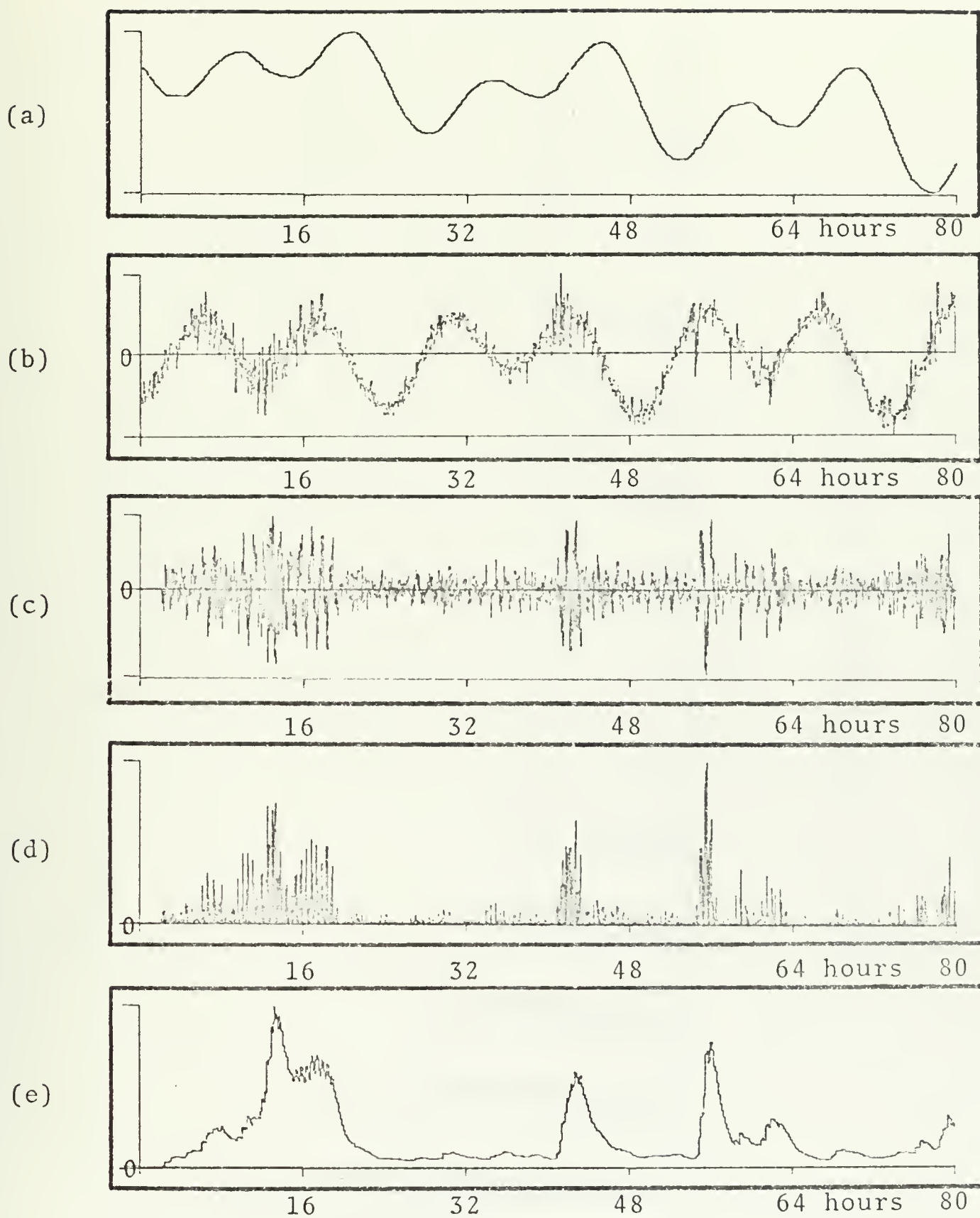


FIGURE 4. (a) Pressure, (b) First Differenced Pressure (Spurious Data Gate On), (c) Tide Filtered Pressure, (d) Squared Tide Filtered Pressure, (e) Integrated Pressure Versus Time in Hours.



FIGURE 5. Power Spectrum of Tide Filter.



FIGURE 6. Power Spectrum of Detector Output.

APPENDIX

```

SUBROUTINE ANTIDE (FILE,Y,TIDE,L)
PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE TIDE
   DEPENDENT DATA WHICH IS TO BE FILTERED.
TIDE = A REAL, SINGLY DIMENSIONED ARRAY INTO WHICH THE TIDE
       FILTERED DATA IS TO BE PLACED. ARRAYS Y AND TIDE MAY
       BE THE SAME PHYSICAL ARRAY.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY Y.

DESCRIPTION ANTIDE (ANTI-TIDE) REMOVES THE EFFECTS OF THE DIURNAL
SUBROUTINE ANTIDE (ANTI-TIDE) REMOVES THE EFFECTS OF THE DIURNAL
AND SEMI-DIURNAL TIDES ON THE DATA IN ARRAY Y AND RETURNS THE TIDE
FILTERED DATA IN ARRAY TIDE. THE FIRST 120 ELEMENTS OF ARRAY TIDE
ARE SET TO ZERO SINCE A 2 HOUR HISTORY OF DATA VALUES IS NECESSARY
TO REMOVE THE EFFECTS OF THE TIDES. THE PROPER TIME SCALE IS
ALSO MAINTAINED.

REAL Y(L), TIDE(L)
LM120=L-120
DO 10 I=1,LM120
  J=L-I+1
  TIDE(J)=Y(J)-3.920392*Y(J-30)+5.8418*Y(J-60)
             -3.920392*Y(J-90)+Y(J-120)
10 CONTINUE
DO 20 I=1,120
  TIDE(I)=0.0
20 CONTINUE
WRITE(6,1) FILE
FORMAT(1H0,'FILE ',F4.1,' TIDE FILTERED')
1 RETURN
END

```



```

C      SUBROUTINE CARDS (FILE,Y,L)
C
C      PARAMETERS
C      FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
C              (FOR USER IDENTIFICATION PURPOSES ONLY.)
C      Y    = A REAL, SINGLY DIMENSIONED ARRAY INTO WHICH THE DATA IS
C              TO BE READ.
C      L    = AN INTEGER VARIABLE EQUAL TO THE NUMBER OF ELEMENTS TO
C              BE READ INTO ARRAY Y.
C
C      DESCRIPTION CARDS READS FROM THE CARD READER (DEVICE 5), "L"
C      SUBROUTINE IN THE PRESENT CONFIGURATION, ONE LOGICAL RECORD
C      ELEMENTS. IN THE FORM 10F7.0,F10.0 (SEE FORMAT 1).
C
C      REAL Y(L)
C      FORMAT(10F7.0,F10.0)
C      FORMAT(1H1,'READING FILE ',F4.1)
C      FORMAT(1H0,'END OF FILE ',F4.1,' - ',I5,' CARDS READ')
C      WRITE(6,2) FILE
C      NCARDS=0
C      IFIRST=1
C      ILAST=10
C      READ(5,1,ERR=20,END=20)(Y(J),J=IFIRST,ILAST),CARD
C      IFIRST=IFIRST+10
C      ILAST=ILAST+10
C      NCARDS=NCARDS+1
C      IF(ILAST.GT.L) GO TO 20
C      GO TO 10
C      WRITE(6,3) FILE, NCARDS
C      L=IFIRST-1
C      RETURN
C      END

```

CCCCCCCCCCCC

1
2
3

10

20


```

SUBROUTINE DRAW1 (FILE,Y,L,YMAXV,YMINV,LOG,XL,XI)
PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE ORDINATE
  VALUES, TO BE PLOTTED. EQUAL TO THE SIZE OF ARRAY Y.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY Y.
YMAXV, YMINV = THE MAXIMUM AND MINIMUM VALUES TO BE PLOTTED.
      IF YMAXV <= YMINV THEN THE PLOT IS AUTOSCALED.
LOG = AN INTEGER VARIABLE OF VALUE 0 OR 1. (LOG SCALE CODE.)
      IF LOG=1 THEN THE DATA IN ARRAY Y IS PLOTTED ON
      LOG10 SCALE.
XL,XI = REAL ARRAYS CONTAINING LITERAL CONSTANTS. THE MAXIMUM
      CHARACTER STRING LENGTH ALLOWABLE IS 40 CHARACTERS.
      XL: LABEL DESCRIBING THE PLOT (MAY BE BLANK).
      XI: USER IDENTIFICATION (MAY NOT BE BLANK).

```

DESCRIPTION - DRAW1 PLOTS THE DATA CONTAINED IN ARRAY Y VERSUS THE INDEX NUMBER OF THE DATA ON THE CALCOMP MODEL 765. THE LENGTH OF THE X AND Y AXES ARE INITIALLY 20 AND 8 INCHES RESPECTIVELY. THE DATA IS AUTOMATICALLY SCALED ACCORDING TO THE PASSED PARAMETERS YMAXV AND YMINV.

NOTE: THIS SUBROUTINE DOES NOT ALTER THE DATA PASSED TO IT.

```

REAL XL(10),XI(10)
REAL Y(L)
DATA XLN/20./
DATA YLN/8./
FORMAT(1H0,'FILE ',F4.1,' PLOTTED.')
IF(L.LT.20) RETURN
YMAX=YMAXV
YMIN=YMINV
GO TO 8

```

```

ENTRY XYAXIS (XAL,YAL)

```

```

PARAMETERS
XAL = THE LENGTH OF THE X AXIS IN INCHES.
YAL = THE LENGTH OF THE Y AXIS IN INCHES.

```

DESCRIPTION
A CALL ON XYAXIS WITH THE PROPER PARAMETERS WILL CAUSE THE LENGTHS OF THE X AND Y AXES TO BE CHANGED TO THE SPECIFIED SIZE.


```

C
XLN=XAL
YLN=YAL
RETURN
IF(YMAX.LE.YMIN) CALL STATS (FILE,Y,L,YMAX,YMIN,YMEAN,YSTDEV)
IF(YMIN.LT.0.0) LOG=0
IF(YMIN.GT.0.0) LOG=1
C COMPUTE POINTS PER INCH AND RELATIVE ORIGINS (TRUNCATED TO INTEGER)
IF(LOG.EQ.0) GO TO 10
YPI=ALOG10(YMAX-YMIN+1.)/YLN
YORG=ALOG10(YMIN+1.)
GO TO 12
10 YPI=AINT((YMAX-YMIN)/YLN)
YORG=AINT(YMIN)
12 XPI=FLOAT(L/IFIX(XLN))
XORG=0.0
YS=1./YPI
XS=1./XPI
EL=FLOAT(L)
C INITIATE THE PLOT ROUTINE
CALL PLOTS (0.0,0.0,28,XI,0.0,40)
CALL SYMBOL (0.0,0.5,28,XL,0.0,40)
CALL SYMBOL (0.0,1.5,28,FILE,0.0,1)
CALL NUMBER (2.0,1.0,21,TOTAL,POINTS PLOTTED =' ,0.0,22)
CALL NUMBER (6.5,1.0,21,EL,0.0,0)
CALL SYMBOL (2.0,1.3,21,Y SCALE (UNITS/INCH) =' ,0.0,22)
CALL SYMBOL (6.5,1.3,21,YPI,U.0,1)
CALL SYMBOL (2.0,1.6,21,X SCALE (UNITS/INCH) =' ,0.0,22)
CALL NUMBER (6.5,1.6,21,XPI,0.0,1)
CALL PLOT (1.0,3.5,-3)
CALL AXIS (YLN,0.0,1,YLN,180.0,YORG,YPI)
IF(LOG.EQ.1) CALL SYMBOL (2.0,0,-0.6,21,LOG SCALE',180.0,9)
CALL AXIS (YLN,0.0,1,-1,XLN,90.0,XORG,XPI)
IF(YMAX*YMIN.GT.0.0) GO TO 13
S=YLN+YORG*YS
CALL PLOT (S,-125,3)
CALL PLOT (S,XLN,2)
CALL PLOT (S,-125,2)
IF(LOG.EQ.0) GO TO 14
13 YP=YLN-ALOG10(Y(1)-YMIN+1.)*YS
GO TO 15
14 YP=YLN-(Y(1)-YORG)*YS
15 XP=1.*XS
CALL PLOT (YP,XP,3)
DO 20 I=2,L
IF(LOG.EQ.0) GO TO 16
YP=YLN-ALOG10(Y(I)-YMIN+1.)*YS
GO TO 17

```



```

16 YP=YLN-(Y(I)-YORG)*YS
17 XP=(FLOAT(I)-XORG)*XS
20 CALL PLOT (YP,XP,2)
CONTINUE
TOP=XLN+4.
CALL PLOT (-1.,TOP,-3)
CALL PLOT
WRITE(6,1)FILE
FILE=FILE+.1
RETURN
END

```


SUBROUTINE FFREAL (FILE,A,B,N,ISN)

PARAMETERS -

FILE= A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
(FOR USER IDENTIFICATION PURPOSES ONLY.)
A = A REAL ARRAY CONTAINING THE DATA TO BE TRANSFORMED.
ON RETURN, ARRAY A CONTAINS THE COSINE AND SINE CO-
EFFICIENTS OF THE TRANSFORM FOR THE 1ST THROUGH THE
NTH HARMONIC.
B = THE ADDRESS OF THE SECOND ELEMENT OF ARRAY A; I.E. A(2).
N = AN INTEGER VARIABLE EQUAL TO 1/2 THE SIZE OF ARRAY A.
ON RETURN, N MAY BE SLIGHTLY SMALLER THAN THE VALUE
ORIGINALLY PASSED. (SEE SUBPROGRAM FFT.)
ISN = AN INTEGER OF VALUE +2 IF THE REAL TRANSFORM IS TO BE
PERFORMED; -2 IF THE INVERSE TRANSFORM IS DESIRED.

DESCRIPTION - SUBROUTINE FFREAL COMPUTES THE FOURIER TRANSFORM OF
IF ISN=+2, DATA VALUES. THE COSINE AND SINE COEFFICIENTS
2*N REAL AND ARE RETURNED IN ARRAY A. THE RESULTS ARE AUTO-
MATICALLY SCALED BY THE USUAL SCALE FACTOR OF $1/(2*N)$.
IF ISN=-2, SUBROUTINE FFREAL COMPUTES THE INVERSE FOURIER
TRANSFORM. IN THIS CASE THE SCALE FACTOR IS 1/2.
IN BOTH CASES, SUBROUTINE FFT IS CALLED TO PERFORM THE ACTUAL
TRANSFORM.

REFERENCE: R. C. "ALGORITHM FOR MIXED RADIX FFT", IEEE TRANS-
SINGLETON, ON AUDIO AND ELECTROACOUSTICS, VOL. AU-17, NO. 2,
ACT. PP. 93-103, JUNE 1969.

REAL A(1),B(1)
REAL IM
FORMAT(1H0,'FILE ',F4.1,' - FOURIER TRANSFORM')
WRITE(6,2) FILE
INC=IABS(ISN)
SN=0.
IF (ISN.LT.0) GO TO 30
CALL FFT (FILE,A,B,N,ISN)
CN=1.0
NK=N*INC+2
NH=NK/2
SD=2.0*ATAN(1.0)/FLOAT(N)
CD=2.0*SIN(SD)**2
SD=SIN(SD+SD)
A(NK-1)=A(1)
B(NK-1)=B(1)
SC=1.0/(2.*N)


```

10      DO 20 J=1,NH,INC
      K=NK-J
      AA=A(J)+A(K)
      AB=A(J)-A(K)
      BA=B(J)+B(K)
      BB=B(J)-B(K)
      RE=CN*BA+SN*AB
      IM=SN*BA-CN*AB
      B(K)=(IM-BB)*SC
      B(J)=(IM+BB)*SC
      A(K)=(AA-RE)*SC
      A(J)=(AA+RE)*SC
      AA=CN-(CD*CN+SD*SN)
      SN=(SD*CN-CD*SN)+SN
      CN=0.5/(AA**2+SN**2)+0.5
      SN=CN*SN
      CN=AA
      IF (ISN.GT.0) RETURN
      CALL FFT (FILE,A,B,N,ISN)
      RETURN
      CN=-1.0
      NK=NK+INC+2
      NH=NH/2
      SD=2.0*ATAN(1.0)/FLOAT(N)
      CD=2.0*SIN(SD)**2
      SD=SIN(SD+SD)
      SD=-SD
      SC=0.5
      GO TO 10
      END
20
30

```


SUBROUTINE FFT (FILE,A,B,N,ISN)

PARAMETERS -
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
A = A REAL ARRAY ORIGINALLY CONTAINING THE REAL COMPONENTS OF
THE DATA. ON RETURN, ARRAY A CONTAINS THE REAL COMPONENTS
OF THE FOURIER TRANSFORM; I.E. THE COSINE COEFFICIENTS.
B = A REAL ARRAY ORIGINALLY CONTAINING THE IMAGINARY COMPONENTS
OF THE DATA. ON RETURN, ARRAY B CONTAINS THE IMAGINARY
COMPONENTS OF THE FOURIER TRANSFORM; I.E. THE SINE
COEFFICIENTS.
N = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY A.
ISN : (SIZE OF ARRAY A = SIZE OF ARRAY B.) STEP SIZE OF DATA IN
THE ARRAYS A AND B. THE SIGN OF ISN DETERMINES WHETHER
THE COMPLEX OR INVERSE TRANSFORM WILL BE PERFORMED.

DESCRIPTION - FFT COMPUTES THE SINGLE-VARIATE COMPLEX FOURIER
TRANSFORM COMPUTED IN PLACE USING A FIXED-RADIX FAST FOURIER
TRANSFORM BY R. C. SINGLETON*. MAY BE SLIGHTLY ALTERED BY THE SUBPROGRAM IN
ORDER THAT ITS PRIME FACTORS SATISFY CERTAIN CONDITIONS.
ARRAYS AT(MAXF), CK(MAXF), BT(MAXF), SK(MAXF), AND NP(MAXP)
ARE USED FOR TEMPORARY STORAGE. IF THE AVAILABLE STORAGE
IS INSUFFICIENT, THE PROGRAM IS TERMINATED BY A STOP.
MAXF MUST BE \geq THE MAXIMUM OF PRIME FACTORS OF N.
MAXP MUST BE \geq THE NUMBER OF PRIME FACTORS OF N.
IN ADDITION, IF THE SQUARE-FREE PORTION OF N HAS TWO OR
MORE PRIME FACTORS, THEN MAXP MUST BE $\geq K-1$.
ARRAY STORAGE FACTOR IN NFAC FOR A MAXIMUM OF 13 PRIME FACTORS OF N.
IF N HAS MORE THAN ONE SQUARE-FREE FACTOR, THE PRODUCT OF THE
SQUARE-FREE FACTORS MUST BE ≤ 210 .
ARRAY STORAGE FOR MAXIMUM PRIME FACTOR OF 23.
REFERENCE:
SINGLETON, R. C., "ALGORITHM FOR MIXED RADIX FFT", IEEE TRANS-
ACTIONS ON AUDIO AND ELECTROACOUSTICS, VOL. AU-17, NO. 2,
PP. 93-103, JUNE 1969.

REAL A(1),B(1)
DIMENSION NFAC(13),NP(209)

CC


```

C1 DIMENSION AT(23),CK(23),BT(23),SK(23)
C2 EQUIVALENCE (I,II)
C    SET NFAC TO ZERO
DO 2 I=1,13
NFAC(I)=0
NTOT=N
NSPAN=N
C THE FOLLOWING TWO CONSTANTS SHOULD AGREE WITH THE ARRAY DIMENSIONS.
MAXF=23
MAXP=209
C
4 IF (ISN .EQ. 0) GO TO 998
INC=ISN
C72=0.30901699437494742
S72=0.95105651629515357
S120=0.86602540378443865
RAD=6.2831853071796
IF (ISN .GE. 0) GO TO 10
S72=-S72
S120=-S120
RAD=-RAD
INC=-INC
10 NT=INC*NTOT
KS=INC*NSPAN
KSPAN=KS
NN=NT-INC
JC=KS/N
RADF=RAD*FLOAT(JC)*0.5
I=0
JF=0
C DETERMINE THE FACTORS OF N
C
M=0
K=N
GO TO 20
15 M=M+1
NFAC(M)=4
K=K/16
20 IF(K-(K/16)*16 .EQ. 0) GO TO 15
J=3
JJ=9
GO TO 30
25 N=M+1
NFAC(M)=J
K=K/JJ
30 IF(MOD(K,JJ) .EQ. 0) GO TO 25

```



```

J=J+2
JJ=J**2
IF(JJ.LE.K) GO TO 30
IF(K.GT.4) GO TO 40
KT=M
NFAC(M+1)=K
IF(K.NE.1) M=M+1
GO TO 80
40 IF(K-(K/4)*4.NE.0) GO TO 50
M=M+1
NFAC(M)=2
K=K/4
50 KT=M
J=2
60 IF(MOD(K,J).NE.0) GO TO 70
M=M+1
NFAC(M)=J
K=K/J
70 J=((J+1)/2)*2+1
IF(J.LE.K) GO TO 60
80 IF(KT.EQ.0) GO TO 92
J=KT
M=M+1
90 NFAC(M)=NFAC(J)
J=J-1
IF(J.NE.0) GO TO 90
DO 94 I=1,13
IF(NFAC(II).GT.MAXF) GO TO 995
92 CONTINUE
NPROD = NFAC(1)
DO 93 I=2,13
IF(NFAC(II).LT.1) GO TO 96
III=II-1
DO 95 KKK=1,III
IF(NFAC(III).EQ.NFAC(KKK)) GO TO 93
94 CONTINUE
NPROD = NPROD * NFAC(III)
93 CONTINUE
NPROD = NPROD - 1
IF(NPROD.GT.MAXP) GO TO 995
WRITE(6,98) FILE,N,NFAC
98 FORMAT(1H0,'FILE',F4.1,' IN FFT',4X,15,' TERMS',/
.11X,'FACTORS:'/11X,13I5)
C COMPUTE FOURIER TRANSFORM
C
C 100 SD=RADF/FLCAT(KSPAN)
C CD=2.0*SIN(SD)**2

```



```

SD=SIN(SD+SD)
KK=1
I=I+1
IF(NFAC(I) .NE. 2) GO TO 400
C TRANSFORM FOR FACTOR OF 2 (INCLUDING ROTATION FACTOR)
C
KSPAN=KSPAN/2
K1=KSPAN+2
210 K2=KK+KSPAN
AK=A(K2)
BK=B(K2)
A(K2)=A(KK)-AK
B(K2)=B(KK)-BK
A(KK)=A(KK)+AK
B(KK)=B(KK)+BK
KK=K2+KSPAN
IF(KK .LE. NN) GO TO 210
KK=KK-NN
IF(KK .LE. JC) GO TO 210
IF(KK .GT. KSPAN) GO TO 800
220 C1=1.0-CD
S1=SD
K2=KK+KSPAN
AK=A(KK)-A(K2)
BK=B(KK)-B(K2)
A(KK)=A(KK)+A(K2)
B(KK)=B(KK)+B(K2)
A(K2)=C1*AK-S1*BK
B(K2)=S1*AK+C1*BK
KK=K2+KSPAN
IF(KK .LT. NT) GO TO 230
K2=KK-NT
C1=-C1
KK=K1-K2
IF(KK .GT. K2) GO TO 230
AK=CD*C1+SD*S1
S1=(SD*C1-CD*S1)+S1
C1=C1-AK
KK=KK+JC
IF(KK .LT. K2) GO TO 230
K1=K1+INC+INC
KK=(K1-KSPAN)/2+JC
IF(KK .LE. JC+JC) GO TO 220
GO TO 100
C TRANSFORM FOR FACTOR OF 3 (OPTIONAL CODE)
C
C

```



```

320 K1=KK+KSPAN
    K2=K1+KSPAN
    AK=A(KK)
    BK=B(KK)
    AJ=A(K1)+A(K2)
    BJ=B(K1)+B(K2)
    A(KK)=AK+AJ
    B(KK)=BK+BJ
    AK=-0.5*AJ+AK
    BK=-0.5*BJ+BK
    AJ=(A(K1)-A(K2))*S120
    BJ=(B(K1)-B(K2))*S120
    A(K1)=AK-BJ
    B(K1)=BK+AJ
    A(K2)=AK+BJ
    B(K2)=BK-AJ
    KK=K2+KSPAN
    IF(KK.LT.NN) GO TO 320
    KK=KK-NN
    IF(KK.LE.KSPAN) GO TO 320
    GO TO 700

C
C TRANSFORM FOR FACTOR OF 4
C
400 IF(NFAC(I).NE.4) GO TO 600
    KSPNN=KSPAN
    KSPAN=KSPAN/4
    C1=1.0
    S1=0
    420 K1=KK+KSPAN
        K2=K1+KSPAN
        K3=K2+KSPAN
        AKP=A(KK)+A(K2)
        AKM=A(KK)-A(K2)
        AJP=A(K1)+A(K3)
        AJM=A(K1)-A(K3)
        A(KK)=AKP+AJP
        AJP=AKP-AJP
        BKP=B(KK)+B(K2)
        BKM=B(KK)-B(K2)
        BJP=B(K1)+B(K3)
        BJM=B(K1)-B(K3)
        B(KK)=BKP+BJP
        BJP=BKP-BJP
        IF(ISN.LT.0) GO TO 450
        AKP=AKM-BJM
        AKM=AKM+BJM
        BKP=BKM+AJM

```



```

430 BKM=BKM-AJM
    IF(S1.EQ.0) GO TO 460
    A(K1)=AKP*C1-BKP*S1
    B(K1)=AKP*S1+BKP*C1
    A(K2)=AJP*C2-BJP*S2
    B(K2)=AJP*S2+BJP*C2
    A(K3)=AKM*C3-BKM*S3
    B(K3)=AKM*S3+BKM*C3
    KK=K3+KSPAN
    IF(KK.LE.0) GO TO 420
    C2=CD*C1+SD*S1
    S1=(SD*C1-CD*S1)+S1
    C1=C1-C2
    C2=C1**2-S1**2
    S2=2.*C1*S1
    C3=C2*C1-S2*S1
    S3=C2*S1+S2*C1
    KK=KK-NT+JC
    IF(KK.LE.KSPAN) GO TO 420
    KK=KK-KSPAN+INC
    IF(KK.LE.JC) GO TO 410
    IF(KSPAN.EQ.JC) GO TO 800
    GO TO 100
450 AKP=AKM+BJM
    AKM=AKM-BJM
    BKP=BKM-AJM
    BKM=BKM+AJM
    IF(S1.NE.0) GO TO 430
460 A(K1)=AKP
    B(K1)=BKP
    A(K2)=AJP
    B(K2)=BJP
    A(K3)=AKM
    B(K3)=BKM
    KK=K3+KSPAN
    IF(KK.LE.0) GO TO 420
    GO TO 440
C
C TRANSFORM FOR FACTOR OF 5 (OPTIONAL CODE)
C
510 C2=C72**2-S72**2
520 S2=2.*C72*S72
    K1=KK+KSPAN
    K2=K1+KSPAN
    K3=K2+KSPAN
    K4=K3+KSPAN
    AKP=A(K1)+A(K4)
    AKM=A(K1)-A(K4)

```



```

BKP=B(K1)+B(K4)
BKM=B(K1)-B(K4)
AJP=A(K2)+A(K3)
AJM=A(K2)-A(K3)
BJP=B(K2)+B(K3)
BJM=B(K2)-B(K3)
AA=A(KK)
BB=B(KK)
A(KK)=AA+AKP+BJP
B(KK)=BB+BKP+BJP
AK=AKP*C72+BJP*C2+AA
BK=BKP*C72+BJP*C2+BB
AJ=AKM*S72+AJM*S2
BJ=BKM*S72+BJM*S2
A(K1)=AK-BJ
A(K4)=AK+BJ
B(K1)=BK+AJ
B(K4)=BK-AJ
AK=AKP*C2+BJP*C72+AA
BK=BKP*C2+BJP*C72+BB
AJ=AKM*S2-AJM*S72
BJ=BKM*S2-BJM*S72
A(K2)=AK-BJ
A(K3)=AK+BJ
B(K2)=BK+AJ
B(K3)=BK-AJ
KK=K4+KSPAN
IF(KK.LT.NN) GO TO 520
KK=KK-NN
IF(KK.LE.KSPAN) GO TO 520
GO TO 700

C TRANSFORM FOR ODD FACTORS
C
600 K=NFAC(I)
KSPNN=KSPAN
KSPAN=KSPAN/K
IF(K.EQ.3) GO TO 320
IF(K.EQ.5) GO TO 510
IF(K.EQ.JF) GO TO 640
JF=K
SI=RAD/FLOAT(K)
CI=COS(SI)
SI=SIN(SI)
IF(JF.GT.MAXF) GO TO 996
CK(JF)=1.0
SK(JF)=0.0
J=1

```



```

630 CK(J)=CK(K)*C1+SK(K)*S1
    SK(J)=CK(K)*S1-SK(K)*C1
    K=K-1
    CK(K)=CK(J)
    SK(K)=-SK(J)
    J=J+1
    IF(J.LT.K) GO TO 630

640 K1=KK
    K2=KK+KSPNN
    AA=A(KK)
    BB=B(KK)
    AK=AA
    BK=BB
    J=1
    K1=K1+KSPAN
    K2=K2-KSPAN
    J=J+1
    AT(J)=A(K1)+A(K2)
    AK=AT(J)+AK
    BT(J)=B(K1)+B(K2)
    BK=BT(J)+BK
    J=J+1
    AT(J)=A(K1)-A(K2)
    BT(J)=B(K1)-B(K2)
    K1=K1+KSPAN
    IF(K1.LT.K2) GO TO 650
    A(KK)=AK
    B(KK)=BK
    K1=KK
    K2=KK+KSPNN
    J=1
    K1=K1+KSPAN
    K2=K2-KSPAN
    JJ=J
    AK=AA
    BK=BB
    AJ=0.0
    BJ=0.0
    K=1
    K=K+1
    AK=AT(K)*CK(JJ)+AK
    BK=BT(K)*CK(JJ)+BK
    K=K+1
    AJ=AT(K)*SK(JJ)+AJ
    BJ=BT(K)*SK(JJ)+BJ
    JJ=JJ+J
    IF(JJ.GT.JF) JJ=JJ-JF
    IF(K.LT.JF) GO TO 670

```



```

K=JF-J
A(K1)=AK-BJ
B(K1)=BK+AJ
A(K2)=AK+BJ
B(K2)=BK-AJ
J=J+1
IF(J • LT • K) GO TO 660
KK=KK+KSPNN
IF(KK • LE • NN) GO TO 640
KK=KK-NN
IF(KK • LE • KSPAN) GO TO 640

C      MULTIPLY BY ROTATION FACTOR (EXCEPT FOR FACTORS OF 2 AND 4)
C
700  IF(I • EQ • M) GO TO 800
    KK=JC+1
710  C2=1.0-CD
    S1=SD
720  C1=C2
    S2=S1
    KK=KK+KSPAN
730  AK=A(KK)
    A(KK)=C2*AK-S2*B(KK)
    B(KK)=S2*AK+C2*B(KK)
    KK=KK+KSPNN
    IF(KK • LE • NT) GO TO 730
    AK=S1*S2
    S2=S1*C2+C1*S2
    C2=C1*C2-AK
    KK=KK-NT+KSPAN
    IF(KK • LE • KSPNN) GO TO 730
    C2=C1-(CD*C1+SD*S1)
    S1=S1+(SD*C1-CD*S1)
    KK=KK-KSPNN+JC
    IF(KK • LE • KSPAN) GO TO 720
    KK=KK-KSPAN+JC+INC
    IF(KK • LE • JC+JC) GO TO 710
    GO TO 100

C      PERMUTE THE RESULTS TO NORMAL ORDER----DONE IN TWO STAGES
C      PERMUTATION FOR SQUARE FACTORS OF N
C
800  NP(1)=KS
    IF(KT • EQ • C) GO TO 890
    K=KT+KT+1
    IF(M • LT • K) K=K-1
    J=1
    NP(K+1)=JC

```



```

810 NP(J+1)=NP(J)/NFAC(J)
   NP(K)=NP(K+1)*NFAC(J)
   J=J+1
   K=K-1
   IF(J.LT.K) GO TO 810
   K3=NP(K+1)
   KSPAN=NP(2)
   KK=JC+1
   K2=KSPAN+1
   J=1
C
C   PERMUTATION FOR SINGLE-VARIATE TRANSFORM (OPTIONAL CODE)
C
820 AK=A(KK)
   A(KK)=A(K2)
   A(K2)=AK
   BK=B(KK)
   B(KK)=B(K2)
   B(K2)=BK
   KK=KK+INC
   K2=KSPAN+K2
   IF(K2.LT.KS) GO TO 820
830 K2=K2-NP(J)
   J=J+1
   K2=NP(J+1)+K2
   IF(K2.GT.NP(J)) GO TO 830
   J=1
840 IF(KK.LT.K2) GO TO 820
   KK=KK+INC
   K2=KSPAN+K2
   IF(K2.LT.KS) GO TO 840
   IF(KK.LT.KS) GO TO 830
   JC=K3
890 IF(2*KT+1.GE.M) RETURN
   KSPNN=NP(KT+1)
C
C   PERMUTATION FOR SQUARE-FREE FACTORS OF N
C
   J=M-KT
   NFAC(J+1)=1
900 NFAC(J)=NFAC(J)*NFAC(J+1)
   J=J-1
   IF(J.NE.KT) GO TO 900
   KT=KT+1
   NN=NFAC(KT)-1
   IF(NN.GT.MAXP) GO TO 997
   JJ=0
   J=0

```



```

902 GO TO 906
    JJ=JJ-K2
    K2=KK
    K=K+1
    KK=NFAC(K)
904 JJ=KK+JJ
    IF(JJ.GE. K2) GO TO 902
    NP(J)=JJ
906 K2=NFAC(KT)
    K=KT+1
    KK=NFAC(K)
    J=J+1
    IF(J.LE. NN) GO TO 904
C
C DETERMINE THE PERMUTATION CYCLES OF LENGTH GREATER THAN 1
C
    J=0
    GO TO 914
910 K=KK
    KK=NP(K)
    NP(K)=-KK
    IF(KK.NE. J) GO TO 910
    K3=KK
    J=J+1
914 KK=NP(J)
    IF(KK.LT. C) GO TO 914
    IF(KK.NE. J) GO TO 910
    NP(J)=-J
    IF(J.NE. NN) GO TO 914
    MAXF=INC*MAXF
C
C REORDER A AND B, FOLLOWING THE PERMUTATION CYCLES
C
    GO TO 950
924 J=J-1
    IF(NP(J).LT. 0) GO TO 924
    JJ=JC
926 KSPAN=JJ
    IF(JJ.GT. MAXF) KSPAN=MAXF
    JJ=JJ-KSPAN
    K=NP(J)
    KK=JC*K+II+JJ
    K1=KK+KSPAN
    K2=0
928 K2=K2+1
    AT(K2)=A(K1)
    BT(K2)=B(K1)
    K1=K1-INC

```



```

SUBROUTINE HARMON (FILE,Y,YH,L,H1,H2)
PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA TO
   BE ANALYZED.
YH = A REAL, SINGLY DIMENSIONED ARRAY WHICH ON RETURN TO THE
     CALLING PROGRAM CONTAINS THE COMBINED EFFECT OF THE H1
     THROUGH H2 HARMONICS.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY Y.
   SINCE ARRAY YH IS AN APPROXIMATION TO ARRAY Y, THE
   SIZE OF ARRAY YH IS ALSO L.
H1,H2= POSITIVE INTEGER VARIABLES INDICATING WHICH HARMONICS,
        H1 THROUGH H2 INCLUSIVE, OF ARRAY Y ARE TO BE COMPUTED.

```

DESCRIPTION
SUBROUTINE HARMON EXTRACTS THE EFFECTS OF THE SPECIFIED HARMONICS, H1 THROUGH H2 INCLUSIVE, IN A SEMI-PERIODIC INTERVAL OF $L(=2N)$ EQUALLY-SPACED DATA ELEMENTS OVER A PERIOD T , $L/2$ HARMONICS CAN BE EXTRACTED BY FOURIER ANALYSIS. THESE HARMONICS RANGE FROM ZERO CYCLES PERIOD T (FUNDAMENTAL HARMONIC), MEAN SIGNAL, DC) TO $(L-1)/2$ CYCLES PERIOD T (N-TH HARMONIC). SUBROUTINE HARMON FORMS THE FOURIER EXPANSION OF THE DATA FROM THE H1 TO H2 HARMONIC BY SUMMING THE FOURIER COEFFICIENTS RETURNED BY SUBROUTINE FFT. (SEE LINE 16 BELOW)

NOTE: ARRAYS Y AND YH MUST BE PHYSICALLY DIFFERENT ARRAYS.
THE DATA IN ARRAY Y IS ALTERED.

```

REAL Y(L), YH(L)
INTEGER H1, H2, HS
N=L/2
CALL FFREAL (FILE,Y,Y(2),N,+2)
F1=1./FLOAT(L-1)
IF(H1.GT.1) GO TO 10
HS=3
FTI=.5*Y(1)
GO TO 11
HS=H1
FTI=C.0
DO 20 I=1,L
  FT=FTI
  DO 18 J=HS,H2,2
    FT=FT+Y(J)*COS(3.14159*(J-1)*(I-1)*F1)
    +Y(J+1)*SIN(3.14159*(J-1)*(I-1)*F1)
  
```

10
11

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC


```

18      CONTINUE
20      YH(I)=FT
      CONTINUE
1      WRITE(6,1) FILE
      FORMAT(IH0,'FILE ',F4.1,' - HARMONICS ISOLATED')
      RETURN
      END

```



```

SUBROUTINE INTGRL (FILE,X,Y,L,FTC)

PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
X    = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA TO
      BE INTEGRATED.
Y    = A REAL, SINGLY DIMENSIONED ARRAY INTO WHICH THE INTE-
      GRATED, RESULT OF ARRAY X IS PLACED. ARRAYS X AND Y MAY
      BE THE SAME PHYSICAL ARRAY.
L    = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY Y
      = THE SIZE OF ARRAY X.
FTC  = FADING TIME CONSTANT. BY VARYING THE VALUE OF FTC THE
      LENGTH OF THE INTEGRATING INTERVAL CAN EFFECTIVELY BE
      ALTERED.

DESCRIPTION
SUBROUTINE INTGRL PERFORMS INTEGRATION BY COMPUTING THE SUM OF
ALL THE PREVIOUS ELEMENTS AND MULTIPLYING THE SUM BY A CONSTANT
LESS THAN UNITY. THE INTEGRATING FUNCTION IS

      
$$Y(I) = \exp(-FTC) * (Y(I-1) + X(I)) ; I = 1, \dots, L.$$


REAL X(L), Y(L)
XINT=0.0

      DELTA FUNCTION INTEGRATING TECHNIQUE

EFTC=EXP(-FTC)
DO 10 I=1,L
  XINT=EFTC*(XINT+X(I))
  Y(I)=XINT
CONTINUE
WRITE(6,1) FILE, FTC
FORMAT(1H0,'FILE ',F4.1,' INTEGRATED. FTC = ',F7.4)
RETURN
END

```



```

SUBROUTINE OUTPUT (FILE,Y,L)
PARAMETERS -
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y     = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA
      TO BE PRINTED.
L     = AN INTEGER VARIABLE EQUAL TO THE SIZE OF Y.

DESCRIPTION -
SUBROUTINE OUTPUT PRINTS THE DATA CONTAINED IN ARRAY Y. THE
OUTPUT FORMAT IS 4 COLUMNS PER PAGE, 50 NUMBERS PER COLUMN.
(200 DATA ELEMENTS PLUS INDEX NUMBERS PER PAGE.)

REAL Y(L)
FORMAT(1H1,45X,'D A T A F I L E N O. ',F3.1,15X,'PAGE ',
• I2,' OF ',I2,'/',4(4X,'I',14X,'Y(I)',10X),/)
FORMAT(4(1X,I6,7X,E13.6,5X,'|',))
NCOL=(L-1)/50+1
NPAGE=(NCOL-1)/4+1
IPAGE=1
WRITE(6,1) FILE, IPAGE, NPAGE
IF(IPAGE.EQ.NPAGE) GO TO 20
DO 10 I=1,50
N1=(IPAGE-1)*200+I
N2=N1+50
N3=N1+100
N4=N1+150
WRITE(6,2)N1,Y(N1),N2,Y(N2),N3,Y(N3),N4,Y(N4)
CONTINUE
IPAGE=IPAGE+1
GO TO 8
LCOL=NCOL-(IPAGE-1)*4
DO 30 I=1,50
KCOL=LCOL+I
N1=(IPAGE-1)*200+I
N2=N1+50
N3=N1+100
N4=N1+150
IF(N1+(LCOL-1)*50.GT.L) KCOL=KCOL-1
GO TO(30,29,28,27,26),KCOL
WRITE(6,2)N1,Y(N1),N2,Y(N2),N3,Y(N3),N4,Y(N4)
GO TO 30
WRITE(6,2)N1,Y(N1),N2,Y(N2),N3,Y(N3)
GO TO 30
WRITE(6,2)N1,Y(N1),N2,Y(N2)
GO TO 30
WRITE(6,2)N1,Y(N1)
CONTINUE
RETURN
END

```



```

NIP=IDEN-1
LM1=L-1
DO 20 I=1,LM1
  IP=LAST-(I-1)*IDEN
  LI1=L-I+1
  RANGE=Y(LI1-1)-Y(LI1)
  Y2(IP)=Y(LI1)
  DO 10 J=1,NIP
    Y2(IP-J)=Y2(IP)+RANGE*FLOAT(J)/FLOAT(IDEN)
    +RAMP*UNIFORM(ISEED)
  CONTINUE
CONTINUE
Y2(1)=Y(1)
L2=LAST
WRITE(6,1) FILE
RETURN
END
10
20

```



```

SUBROUTINE POWER (FILE,Y,L)
PARAMETERS -
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y     = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA
      WHOSE POWER SPECTRUM IS TO BE COMPUTED.
L     = AN INTEGER VARIABLE EQUAL TO THE SIZE OF Y.

DESCRIPTION -
SUBROUTINE POWER FINDS THE FOURIER TRANSFORM OF THE DATA IN
ARRAY Y. FROM THE TRANSFORM THE POWER SPECTRUM IS COMPUTED.
THE FOURIER COEFFICIENTS ARE COMPUTED BY SUBROUTINE FREAL AND
SUBROUTINE FFT; ALGORITHMS WRITTEN BY R. C. SINGLETON OF THE
STANFORD RESEARCH INSTITUTE.

NOTE: THIS SUBROUTINE ALTERS THE DATA PASSED TO IT.

REAL XL(10),XI(10)
REAL Y(L)
N=L/2
CALL FREAL (FILE,Y,Y(2),N,+2)
DO 10 I=1,N
  Y(I) = .Y(2*I-1)**2 + Y(2*I)**2
CONTINUE
WRITE(6,1) FILE
FORMAT(1H0,'FILE ',F4.1,' - POWER SPECTRUM')
RETURN
END

```

CCCCCCCCCCCCCCCCCCCC

10
1


```

SUBROUTINE RECSQR (FILE,X,Y,L,IRS)
PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
X    = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA TO
      BE SQUARED OR RECTIFIED.
Y    = A REAL, SINGLY DIMENSIONED ARRAY WHICH RECEIVES THE
      SQUARED OR RECTIFIED DATA OF ARRAY X. ARRAYS X AND Y MAY
      BE PHYSICALLY VARIABE SAME ARRAY.
L    = AN INTEGER VARIABLE EQUAL TO 1 OR 2.
      IF IRS = 1 THEN THE ABSOLUTE VALUE OF THE ELEMENT OF
      IF IRS = 2 THEN THE SQUARED VALUE OF THE ELEMENT OF
      ARRAY X IS PLACED IN ARRAY Y.

```

```

DESCRIPTION
SELF-EXPLANATORY

```

```

REAL X(L),Y(L)
IF(IRS.GE.2) GO TO 50
DO 10 I=1,L
  Y(I)=ABS(X(I))
  CONTINUE
WRITE(6,1) FILE
FORMAT(1HC,'FILE ',F4.1,' RECTIFIED')
RETURN
DO 60 I=1,L
  Y(I)=X(I)**2
  CONTINUE
WRITE(6,2) FILE
FORMAT(1HC,'FILE ',F4.1,' SQUARED')
RETURN
END

```

CCCCCCCCCCCCCCCCCCCC

10
1
50
60
2


```

SUBROUTINE RESET (FILE, Y, L, Y2, L2)
PARAMETERS
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA
ELEMENTS.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF ARRAY Y.
Y2 = A REAL, SINGLY DIMENSIONED ARRAY INTO WHICH ARRAY Y WILL
    BE RESET. ARRAYS Y AND Y2 MAY BE PHYSICALLY AND/OR
    LOGICALLY THE SAME ARRAY.
L2 = AN INTEGER VARIABLE WHOSE VALUE ON INPUT INDICATES WHICH
    ELEMENT OF ARRAY Y WILL BE THE FIRST ELEMENT OF ARRAY Y2.
    ON RETURN, L2 EQUALS THE SIZE OF ARRAY Y2.

```

```

DESCRIPTION -
SELF-EXPLANATORY

```

```

REAL Y(L), Y2(L)
FORMAT(1H0, 'FILE ', F4.1, ' RESET BY ', I4)
IF(L2.LT.0) RETURN
LAST=L-L2
DO 10 I=1, LAST
Y2(I)=Y(I+L2)
CONTINUE
WRITE(6,1) FILE, L2
L2=LAST
RETURN
END

```

```

CCCCCCCCCCCCCCCCCCCC

```

1

10


```

SUBROUTINE SCAN (FILE,Y,L,YMEAN,YSTDEV,L2)

PARAMETERS -
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA
   TO BE FILTERED.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF Y.
YMEAN, YSTDEV = THE MEAN AND STANDARD DEVIATION OF THE DATA
   CONTAINED IN ARRAY Y AS RETURNED BY SUBROUTINE STATS.
L2 = AN INTEGER VALUE WHOSE RETURNED VALUE IS EQUAL TO THE
   NUMBER OF DATA ELEMENTS FILTERED FROM THE BEGINNING OF
   THE ARRAY.

DESCRIPTION - SCAN DETERMINES THE EXTENT OF ANY NOISE PRESENT
ON THE TAPE DUE TO INITIAL START UP OF THE RECORDING DEVICE.
THE FILTER CAN BE DESCRIBED AS BEING A TWO SIGMA FILTER. THAT IS,
FOR EACH ELEMENT IN THE INPUT ARRAY THE FOLLOWING TEST IS MADE:

      IF ABS( Y(I) - YMEAN ) > 2 * YSTDEV )
      THEN INCREASE ITEST BY 1;
      OTHERWISE, SET ITEST = 0.

      IF ITEST EVER REACHES AN ARBITRARY, PRESET VALUE (IN THIS
CASE 100) THE TEST IS TERMINATED. L2 IS THE SET EQUAL TO THE
INDEX OF THE FIRST VALUE TO PASS THE TEST.

REAL Y(L)
FORMAT(IH0,'FILE ',F4.1,' SCANNED. INITIAL ',I5,' SAMPLES NOISE
DEPENDENT. ')
ITEST=0
SPREAD=2.*YSTDEV
DO 20 I=1,L
  IF(ABS(Y(I)-YMEAN).GT.SPREAD) GO TO 10
  ITEST=ITEST+1
  IF(ITEST.GT.100) GO TO 30
  GO TO 20
ITEST=0
L2=I
CONTINUE
WRITE(6,1) FILE,L2
RETURN
END

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC

1

10

20
30


```

SUBROUTINE STATS (FILE,Y,L,YMAX,YMIN,YMEAN,YSTDEV)
PARAMETERS -
FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
      (FOR USER IDENTIFICATION PURPOSES ONLY.)
Y = A REAL, SINGLY DIMENSIONED ARRAY CONTAINING THE DATA
   WHOSE STATISTICS ARE TO BE COMPUTED.
L = AN INTEGER VARIABLE EQUAL TO THE SIZE OF Y.
YMAX = A REAL VARIABLE WHOSE RETURNED VALUE IS EQUAL TO THE
      MAXIMUM VALUE OF Y.
YMIN = A REAL VARIABLE WHOSE RETURNED VALUE IS EQUAL TO THE
      MINIMUM VALUE OF Y.
YMEAN = A REAL VARIABLE WHOSE RETURNED VALUE IS EQUAL TO THE
      STATISTICAL MEAN OF THE DATA CONTAINED IN Y.
YSTDEV = A REAL VARIABLE WHOSE RETURNED VALUE IS EQUAL TO THE
      STANDARD DEVIATION OF THE DATA CONTAINED IN Y.

```

```

DESCRIPTION - STATS COMPUTES THE REQUIRED STATISTICS (MAXIMUM
SUBROUTINE VALUES, MEAN, AND STANDARD DEVIATION) OF ARRAY Y
FOR USE IN SUBROUTINE DRAW1 AND SCAN.

```

```

REAL Y(L)
FORMAT(1H0,'FILE ',F4.1,' STATISTICS:','/
1H0,10X,'(BASED ON SAMPLE SIZE OF ',I5,')'/'
1H0,10X,'MAXIMUM VALUE ',E13.6/
1H0,10X,'MINIMUM VALUE ',E13.6/
1H0,10X,'MEAN ',E13.6/
1H0,10X,'STANDARD DEVIATION ',E13.6)
YMAX=Y(1)
YMIN=Y(1)
YMEAN=Y(1)
SSQUS=Y(1)**2
DO 10 I=2,L
  IF(Y(I).GT.YMAX) YMAX=Y(I)
  IF(Y(I).LT.YMIN) YMIN=Y(I)
  YMEAN=YMEAN+Y(I)
  SSQUS=SSQUS+Y(I)**2
CONTINUE
YMEAN=YMEAN/FLOAT(L)
YSTDEV=SQRT((SSQUS-FLOAT(L)*YMEAN*YMEAN)/FLOAT(L-1))
WRITE(6,1) FILE, L, YMAX, YMIN, YMEAN, YSTDEV
RETURN
END

```

CCCCCCCCCCCCCCCCCCCC

1

1C

SUBROUTINE TAPE (FILE,Y,L)

PARAMETERS -
 FILE = A REAL VARIABLE IDENTIFYING THE CURRENT DATA FILE.
 (FOR USER IDENTIFICATION PURPOSES ONLY.)
 Y = A REAL, SINGLY DIMENSIONED ARRAY WHOSE ELEMENTS ARE
 ASSIGNED FROM THE INPUT TAPE.
 L = AN INTEGER VARIABLE INDICATING THE SIZE OF Y.

DESCRIPTION - TAPE READS IN DATA FROM LOGICAL INPUT DEVICE 2 AND
 SUBROUTINE DATA TO ARRAY Y IN LINEAR SEQUENCE. FORMAT STATEMENT
 ASSIGNS THIS DATA TO ARRAY Y IN LINEAR SEQUENCE. FORMAT STATEMENT
 I MUST REPRESENT THE FORMAT OF EACH LOGICAL INPUT RECORD. THE
 INCREMENT ON IFIRST AND ILAST AS WELL AS THE IMPLIED DO LOOP IN
 STATEMENT LABELED 10, SHOULD BE COMPATIBLE WITH FORMAT 1.
 THE VALUES OF L ON INPUT TO THE SUBROUTINE SHOULD BE THE SIZE
 OF THE PASSED ARRAY AS DIMENSIONED IN THE MAIN PROGRAM. THE
 RETURNED VALUE OF L IS SET EQUAL TO THE ACTUAL SIZE OF THE ARRAY
 AS READ IN FROM TAPE.
 THE FOLLOWING 3 CARDS ARE AN EXAMPLE OF THE JOB CONTROL
 LANGUAGE (JCL) CARDS REQUIRED TO READ FROM A TAPE DRIVE.
 THESE ARE ONLY SAMPLE CARDS.

```
//GO.FT02F001 DD UNIT=2400-1,VOL=SER=TAPENAME,LABEL=(1,NL),
// DCB=(DEN=1,RECFM=F,BLKSIZE=80,TRTCH=ET),
// DISP=(NEW,KEEP),DSN=DATA1
```

```
1 REAL Y(L)
2 FORMAT(10F7.0,F10.0)
3 FORMAT(1H0,'READING FILE NO.',F4.1,' - FIRST RECORD NO. =',F10.0)
4 FORMAT(1H0,'DATA FILE NO.',F4.1,' EMPTY - PROCEEDING TO NEXT FILE
5 .)
6 FORMAT(1H0,'ERROR IN RECORD NO.',I5,' - RECORD SKIPPED')
7 FORMAT(1H0,'END OF FILE NO.',F4.1,' - LAST RECORD NO. =',F10.0,
8 /1H0,41X,I10,' RECORDS READ')
9 WRITE(6,6)
10 WREC=1
11 GO TO 10
12 WRITE(6,3) FILE
13 READ(2,1,ERR=10,END=8) (Y(J),J=1,10),REC1
14 WRITE(6,2) FILE, REC1
15 IFIRST=11
16 ILAST=20
17 NREC=NREC+1
18 READ(2,1,ERR=30,END=40)(Y(J),J=IFIRST,ILAST),RECNO
19 IFIRST=IFIRST+10
```



```

30  ILAST=ILAST+10
    IF (ILAST.GT.L) GO TO 40
    GO TO 20
    WRITE(6,4) NREC
    GO TO 20
    WRITE(6,5) FILE, RECNO, NREC
    L=IFIRST-1
    RETURN
    END
40

```



```
C  
C  
C      FUNCTION UNIFORM (ISEED)  
C      COMPUTE A RANDOM NUMBER BETWEEN -.5 AND +.5  
C      ISEED=ISEED*103941  
C      UNIFORM=FLOAT(ISEED)*.2328306E-9  
C      RETURN  
C      END
```


COMPUTER OUTPUT

```

READING FILE 1.1
END OF FILE 1.1 - 143 CARDS READ
FILE 1.1 STATISTICS:
      (BASED ON SAMPLE SIZE OF 1430)
      MAXIMUM VALUE      0.242438E 06
      MINIMUM VALUE      0.289400E 04
      MEAN                0.151055E 06
      STANDARD DEVIATION  0.807798E 04
      FILE 1.1 SCANNED. INITIAL 57 SAMPLES NOISE DEPENDENT.
      FILE 1.1 RESET BY 210
      FILE 1.1 PACKED
      FILE 1.1 STATISTICS:
            (BASED ON SAMPLE SIZE OF 4800)
            MAXIMUM VALUE      0.153502E 06
            MINIMUM VALUE      0.146354E 06
            MEAN                0.150517E 06
            STANDARD DEVIATION  0.443372E 04
      FILE 1.1 PLOTTED
      FILE 1.2 FIRST DIFFERENCED
      FILE 1.2 STATISTICS:
            (BASED ON SAMPLE SIZE OF 4800)
            MAXIMUM VALUE      0.230000E 02
            MINIMUM VALUE      -0.240000E 02
            MEAN                -0.874531E 00
            STANDARD DEVIATION  0.924408E 01

```



```

FILE 1.2 PLOTTED
FILE 1.3 TIDE FILTERED
FILE 1.3 STATISTICS:
      (BASED ON SAMPLE SIZE OF 4800)
      MAXIMUM VALUE      0.104613E 03
      MINIMUM VALUE      -0.125172E 03
      MEAN                -0.349230E-01
      STANDARD DEVIATION  0.240215E 02

FILE 1.3 PLOTTED
FILE 1.4 SQUARED
FILE 1.4 STATISTICS:
      (BASED ON SAMPLE SIZE OF 4800)
      MAXIMUM VALUE      0.156681E 05
      MINIMUM VALUE      0.0
      MEAN                0.576913E 03
      STANDARD DEVIATION  0.129861E 04

FILE 1.4 PLOTTED
FILE 1.5 INTEGRATED.  FTC = 0.0167
FILE 1.5 STATISTICS:
      (BASED ON SAMPLE SIZE OF 4800)
      MAXIMUM VALUE      0.194251E 06
      MINIMUM VALUE      0.0
      MEAN                0.337821E 05
      STANDARD DEVIATION  0.367765E 05

```


COMPUTER PROGRAM

```

FILE 1.5 PLOTTED
FILE 1.6 - FOURIER TRANSFORM
FILE 1.6 IN FFT. 2400 TERMS
FACTORS: 4 5 2 3 5 4 0 0 0 0 0 0 0
FILE 1.6 - POWER SPECTRUM
FILE 1.6 STATISTICS:
(BASED ON SAMPLE SIZE OF 2400)
MAXIMUM VALUE 0.536683E 02
MINIMUM VALUE 0.167696E-06
MEAN 0.480947E 00
STANDARD DEVIATION 0.228523E 01

FILE 1.6 PLOTTED
FILE 1.7 - FOURIER TRANSFORM
FILE 1.7 IN FFT. 2400 TERMS
FACTORS: 4 5 2 3 5 4 0 0 0 0 0 0 0
FILE 1.7 - POWER SPECTRUM
FILE 1.7 STATISTICS:
(BASED ON SAMPLE SIZE OF 2400)
MAXIMUM VALUE 0.456679E 10
MINIMUM VALUE 0.471905E 00
MEAN 0.302887E 07
STANDARD DEVIATION 0.953146E 08

FILE 1.7 PLOTTED
FINIS.

```



```

C      MAIN PROGRAM - UNUSUAL EVENT DETECTOR
C      ARRAYS C1 THRU C6 HOLD UP TO 40 CHARACTERS EACH FOR PLOT LABELS.
C      REAL C1(10), C2(10), C3(10), C4(10), C5(10), C6(10)
C      WORKING ARRAY DECLARATIONS
C      REAL Y(5000), DIFF(5000), TIDE(5000), YISE(5000)
C      Y - RAW PRESSURE DATA
C      DIFF - FIRST DIFFERENCED DATA
C      TIDE - TIDE FILTERED DATA
C      YISE - UNUSUAL EVENT DETECTOR OUTPUT
C      EQUIVALENCE (Y(1), DIFF(1), YISE(1))
C      THIS EQUIVALENCE STATEMENT CONSERVES STORAGE
C
C      FORMAT('OFINIS.')
C      FORMAT(10A4)
C
C      READ IN LABELS FOR PLOTS AND ASSIGN NUMBER OF FILES
C
C      READ(5,2) C1, C2, C3, C4, C5, C6
C      NFILES=1
C
C      DO 100 K=1, NFILES
C      FILE=FLOAT(K)+0.1
C      SET L EQUAL TO THE NUMBER OF DATA ELEMENTS TO BE READ
C      L=1430
C      SET LMAX TO THE MAXIMUM SIZE OF ARRAY Y
C      LMAX=5000
C
C      CALL CARDS (FILE,Y,L)
C
C      INITIAL SCAN OF DATA
C
C      CALL STATS (FILE,Y,L,YMAX,YMIN,YMEAN,YSTDEV)
C      CALL SCAN (FILE,Y,L,YMEAN,YSTDEV,L2)
C      RESET THE DATA BY 210 MINUTES
C      L2=210
C      CALL RESET (FILE,Y,L,Y,L2)
C      CALL THE INTERVAL TO 1 MINUTE SAMPLES
C      PACK THE INTERVAL (FILE,Y,L2,Y,LMAX, 4, 0.0, 103941)
C      CALL PACK (FILE,Y,L2,Y,LMAX, 4, 0.0, 103941)
C
C      SET THE INTERVAL TO 80 HOURS (4800 MINUTES)
C      L=MINO(4800,LMAX)
C
C      INITIAL PLOT OF DATA
C
C      CALL XYAXIS (5.,1.)
C      CALL DRAW1 (FILE,Y,L,0.,0.,0,C1,C6)

```



```

C C FIRST DIFFERENCING
C C
C C THRESH=25.
C C CALL FIRSTD (FILE,Y,DIFF,L,THRESH)
C C CALL DRAW1 (FILE,DIFF,L,0.,0.,0,C2,C6)
C C
C C TIDE FILTER
C C
C C CALL ANTIDE (FILE,DIFF,TIDE,L)
C C CALL DRAW1 (FILE,TIDE,L,0.,0.,0,C3,C6)
C C
C C SQUARE TIDE FILTER OUTPUT
C C
C C IRS=2
C C CALL RECSQR (FILE,TIDE,YISE,L,IRS)
C C CALL DRAW1 (FILE,YISE,L,0.,0.,0,C3,C6)
C C
C C INTEGRATE TIDE FILTER OUTPUT
C C
C C FTC=1./60.
C C CALL INTGRL (FILE,YISE,YISE,L,FTC)
C C CALL DRAW1 (FILE,YISE,L,0.,0.,0,C4,C6)
C C
C C POWER SPECTRUM OF TIDE FILTER AND DETECTOR OUTPUT
C C
C C CALL XYAXIS (8.,4.)
C C N=L/2
C C CALL POWER (FILE,TIDE,L)
C C CALL DRAW1 (FILE,TIDE,N,0.,0.,1,C5,C6)
C C CALL POWER (FILE,YISE,L)
C C CALL DRAW1 (FILE,YISE,N,0.,0.,1,C5,C6)
C C
C 100 CONTINUE
C WRITE(6,1)
C STOP
C END

```


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Spurious Data Rejection

Tsunami

Real Time Series

Spectral Analysis

Nyquist Frequency

94 NVF 61

23897

26436

128334

Thesis

A653

Arfman

c.1

A software package
for analysis of geo-
physical measurements.

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